

Date am / pm

Course Hand: Port / Starboard

Triangle: 45 / 60 deg

Wind Bearing

Ref Point

Bottom Mark is Reference

		Top Mark
		GPS
Bearing = Wind Bearing	<input type="text"/>	
Back Bearing (to Bottom Mark)	<input type="text"/>	
Distance from Bottom Mark (beat length)	<input type="text"/>	

Wing/Gybe Mark

		GPS
XXX = Internal Angle of Bottom to Wing	<input type="text"/>	
Bearing = Wind Bearing +/- XXX #	<input type="text"/>	
Back Bearing (to Bottom Mark)	<input type="text"/>	
Distance from Bottom Mark (reach length)	<input type="text"/>	
# - for Port Course		
+ for Starbord Course		
reach = beat for 60 degrees		
reach = 0.7 beat for 45 degrees		

Top Mark is Reference

		Bottom Mark
		GPS
Bearing (to Top Mark) = Wind Bearing	<input type="text"/>	
Distance from Top Mark (beat length)	<input type="text"/>	

Wing/Gybe Mark

		GPS
XXX = Internal Angle of Top to Wing	<input type="text"/>	
Bearing = Wind Bearing +/- XXX #	<input type="text"/>	
Distance from Bottom Mark (reach length)	<input type="text"/>	
# + for Port Course		
- for Starbord Course		
reach = beat for 60 degrees		
reach = 0.7 beat for 45 degrees		